

- PHILIPPE BALBIANI, AND TINKO TINCHEV, *Computability of contact logics with measure*.

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Contact logics [1] are propositional logics interpreted over Boolean contact algebras [3]. They stem from the point-free approaches of geometry put forward by Whitehead. Their language $\mathcal{L}(\leq, C)$ includes Boolean terms representing regions. Let \mathbf{X} be a set of variables. The set of Boolean terms (s, t , etc) over \mathbf{X} being denoted $\mathbf{T}(\mathbf{X})$, the set $\mathbf{A}(\mathbf{X})$ of atomic formulas over \mathbf{X} consists of all expressions of the form $s \leq t$ (“ s is part-of t ”) and $C(s, t)$ (“ s is in contact with t ”). The set of all formulas (φ, ψ , etc) over \mathbf{X} is the least set $\mathbf{F}(\mathbf{X})$ containing $\mathbf{A}(\mathbf{X})$ and such that for all $\varphi, \psi \in \mathbf{F}(\mathbf{X})$: $\perp \in \mathbf{F}(\mathbf{X})$, $\neg\varphi \in \mathbf{F}(\mathbf{X})$ and $(\varphi \vee \psi) \in \mathbf{F}(\mathbf{X})$. Of interest are, of course, the sets of all valid formulas determined by the various classes of Boolean contact algebras one may consider. See [1, 5] for detailed investigations.

The combination of topological and size information is a fundamental issue for multifarious applications of spatial reasoning [4]. It can be realized by considering Boolean contact algebras with measure, i.e. algebraic structures (A, C, μ) where (A, C) is a Boolean contact algebra and μ is a positive finite measure on A . Contact logics with measure are extensions of contact logics. Their language $\mathcal{L}(\leq, C, \leq_m)$ contains all additional atomic formulas of the form $s \leq_m t$ (“the size of s is less or equal than the size of t ”). Of interest are, again, the sets of all valid formulas determined by the various classes of Boolean contact algebras with measure one may consider.

Using complexity results about linear programming [2], we show that the set of all valid formulas determined by the class of all Boolean contact algebras with measure is in **coNP**. Our proof relies on the equivalence between the satisfiability of a given formula φ and the consistency of an associated system \mathcal{S}_φ of linear inequalities. It uses the following facts: the computation of \mathcal{S}_φ from φ is possible in non-deterministic polynomial time; if a system of k linear inequalities with integer coefficients of length at most n has a non-negative solution then it has a non-negative solution with at most k positive entries of length in $\mathcal{O}(k.(n + \log k))$.

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[5] KONTCHAKOV, R., I. PRATT-HARTMANN, and M. ZAKHARYASCHEV, ‘Spatial reasoning with *RCC8* and connectedness constraints in Euclidean spaces’, *Artificial Intelligence* **217** (2014) 43–75.